

Force

- » Peak: 312 - 780 N
- » Continuous: 51 - 102N

Maximum Velocity

- » Up to 8.7 m/s

Feedback

- » Built-in position sensor
- » 1V pk-pk sin/cos
- » 12 micron repeatability

Range of motion

- » Travel lengths up to 1200 mm

Dimensions

- » W x H: 54 x 95mm
- » Rod diameter: 25mm

Applications

- » Packaging
- » Material Handling
- » Automated Assembly
- » Bio-medical

The OEM advantage

- » Reliable and cost-effective
- » Flexible position control
- » High speed and acceleration
- » Clean, quiet operation
- » No maintenance or adjustment



ServoTube delivers the speed of a belt-drive system with the clean reliability of a linear forcer at a price unprecedented in the industry. Familiar form factor, integral position feedback and large air gap make installation simple.

The ServoTube forcer components consist of an IP67 rated forcer and a sealed stainless steel thrust rod enclosing rare-earth magnets. Four models deliver a continuous force range of 51~102 N (11~23 lb) with peak forces up to 780 N (175 lb). A range of Thrust Rods are available for travel lengths up to 1200mm.

The magnetic design of ServoTube generates 12 micron (0.47 mil) repeatability and 350 micron (14 mil) accuracy from a non-contact, integral position sensor. No external encoder is required. Position output is industry standard 1V pk-pk sin/cos signals.

ServoTube is an ideal OEM solution for easy integration into pick-and-place gantries and general purpose handling machines. The load is mounted directly to the forcer typically supported by a single bearing rail. The Thrust Rod is mounted at both ends, similar to a ballscrew. A large air gap reduces alignment constraints.

The tubular forcer has superior thermal efficiency, radiating heat uniformly. High duty cycles are possible without the need for forced-air or water cooling.

ELECTRICAL SPECIFICATIONS

FORCER TYPE	2504		2506		2508		2510		units
	S ⁽¹⁾	P ⁽¹⁾	S ⁽¹⁾	P ⁽¹⁾	S ⁽¹⁾	P ⁽¹⁾	S ⁽¹⁾	P ⁽¹⁾	
Peak force @ 25°C ambient for 1 sec	312	156	468	234	624	312	780	390	N
Peak current @ 25°C ambient for 1 sec	20		20		20		20		Apk
With 25 x 25 x2.5cm heatsink plate									
Continuous stall force @ 25°C ambient ⁽²⁾	51.2		69.5		86.4		102.4		N
Continuous stall current @ 25°C ambient	2.31	4.62	2.10	4.20	1.96	3.92	1.86	3.72	Arms
	3.27	6.54	2.97	5.94	2.77	5.54	2.62	5.24	Apk
Without heatsink plate									
Continuous stall force @ 25°C ambient ⁽²⁾	42.5		59.5		75.1		90.0		N
Continuous stall current @ 25°C ambient	1.92	3.84	1.80	3.60	1.70	3.40	1.63	3.26	Arms
	2.72	5.44	2.54	5.08	2.41	4.82	2.31	4.62	Apk
Force constant (sine commutation)	22.1	11.0	33.1	16.5	44.1	22.0	55.2	27.6	N/Arms
	15.6	7.8	23.4	11.7	31.2	15.6	39.0	19.5	N/Apk
Back EMF constant (phase to phase)	18.0	9.0	27.0	13.5	36.0	18.0	45.0	22.5	Vpk/m/s
Fundamental forcer constant	6.47		7.92		9.13		10.24		N/√W
Eddy current loss	9.51		12.55		15.58		18.61		N/m/s
Resistance @ 25°C (phase to phase)	6.02	1.50	9.02	2.25	12.03	3.01	15.04	3.76	Ohm
Resistance @ 100°C (phase to phase)	7.75	1.94	11.63	2.91	15.51	3.88	19.39	4.85	Ohm
Inductance @ 1kHz (phase to phase)	3.90	0.97	5.85	1.46	7.80	1.95	9.75	2.44	mH
Electrical time constant	0.65		0.65		0.65		0.65		ms
Maximum working voltage	380		380		380		380		V d.c.
Pole pitch (one electrical cycle)	51.2		51.2		51.2		51.2		mm
Peak acceleration ⁽³⁾	223	111	223	111	235	117	256	128	m/s ²
Maximum speed ⁽⁴⁾	8.7	7.3	6.5	7.2	5.4	7.6	4.6	7.0	m/s

Notes:

- ⁽¹⁾ S=series forcer phases, P=parallel forcer phases
⁽²⁾ Reduce continuous stall force to 89% at 40°C ambient
⁽³⁾ Based on a moving forcer and no payload
⁽⁴⁾ Based on a moving forcer with triangular move over maximum stroke and no payload

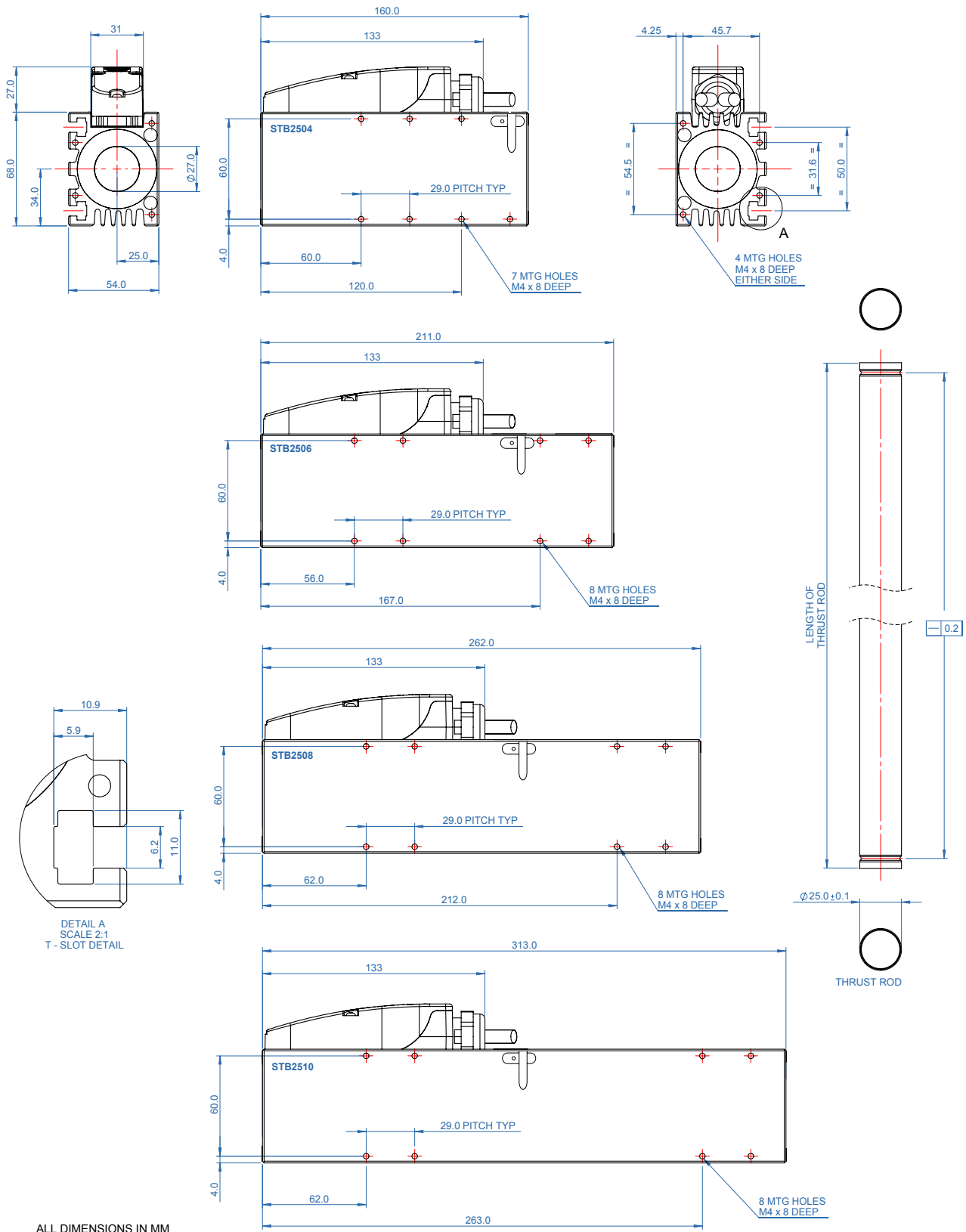
THERMAL SPECIFICATIONS

FORCER TYPE	2504	2506	2508	2510	units
Maximum phase temperature	100	100	100	100	°C
Thermal resistance Rth _{phase-housing}	0.41	0.27	0.20	0.16	°C/Watt
With 25 x 25 x2.5cm heatsink plate					
Power dissipation @ 25°C ambient	62.3	77.0	89.2	100.2	Watt
Thermal resistance Rth _{housing-ambient}	0.79	0.69	0.64	0.59	°C/Watt
Without heatsink plate					
Power dissipation @ 25°C ambient	43.1	56.4	67.6	77.3	Watt
Thermal resistance Rth _{housing-ambient}	1.33	1.06	0.91	0.81	°C/Watt
Thermal time constant	1188	1276	1377	1486	s

MECHANICAL SPECIFICATIONS

FORCER TYPE	2504	2506	2508	2510	units
Maximum stroke	1180	1129	1078	1027	mm
Forcer mass (including bearings)	1.40	2.10	2.65	3.05	kg
Forcer mass (excluding bearings)	1.15	1.60	2.15	2.55	kg
Thrust rod mass/metre	3.5	3.5	3.5	3.5	kg/m

OUTLINE DRAWINGS

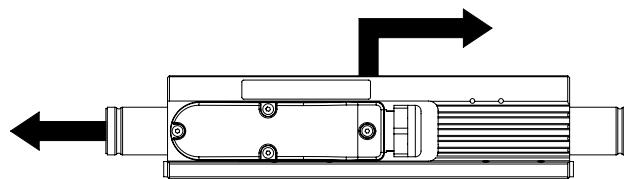
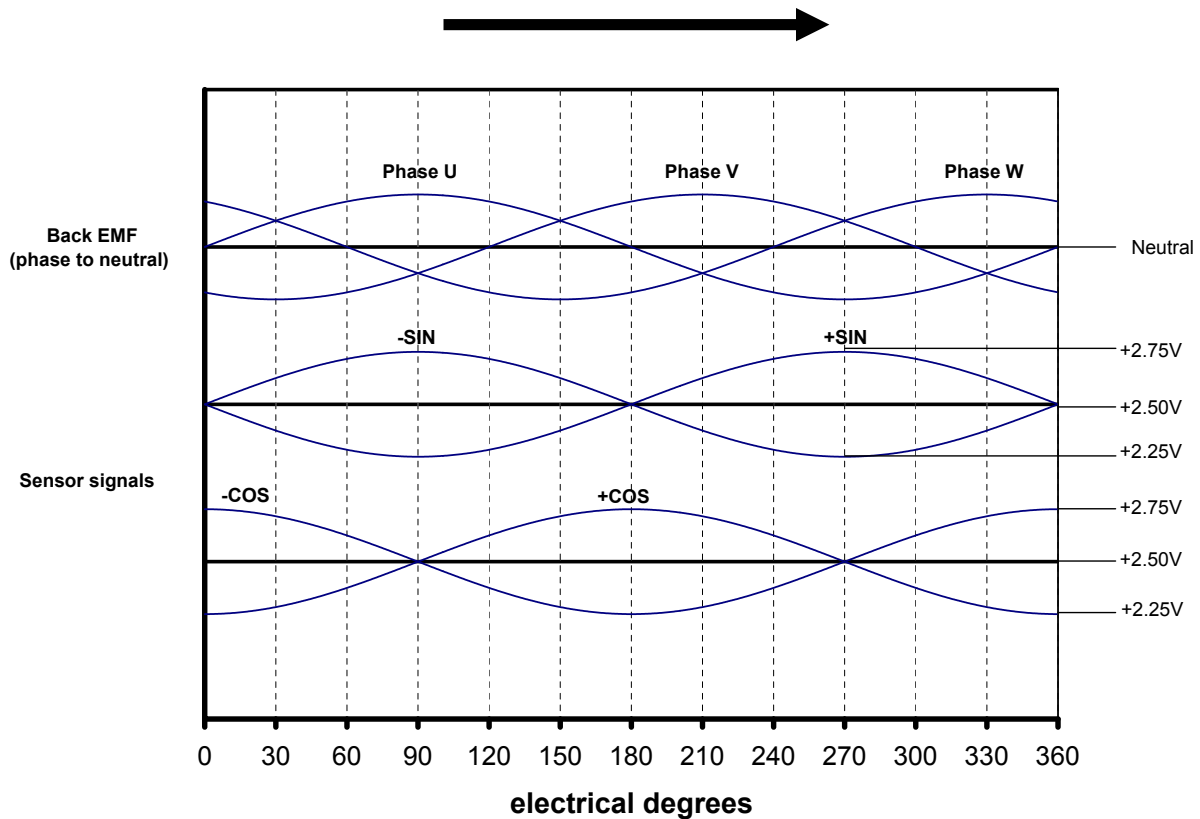


ALL DIMENSIONS IN MM

Available thrust rod lengths see in the catalogue

POSITION SENSOR

The position sensor outputs analogue, differential sine and cosine signals for providing position feedback. Shown below are the relationships between forcer phase back EMF and position sensor outputs for one direction of motion (as shown by arrows). It should be noted that +SIN or -SIN is always in phase with forcer phase U. For the motion shown, -SIN is in phase with forcer phase U. For motion in the opposing direction +SIN is in phase with forcer phase U.



SPECIFICATION	VALUE	units
Output signal period	51.2	mm
Signal amplitude (between +/- signals)	1	Vpk-pk
Output current	± 10	mA
Supply voltage	5 ± 0.25	Vd.c.
Supply current (output current=0)	15 ± 5	mA
Resolution ⁽¹⁾	12	micron
Position repeatability ⁽²⁾	± 12	micron
Absolute accuracy ⁽³⁾	± 350	micron

Notes:

⁽¹⁾ Dependent on amplifier (indication with 12 bit resolution)

⁽²⁾ Dependent on amplifier. Under constant operating conditions. Self-heating of the forcer will cause expansion in the thrust rod during the initial warm up period. In high duty applications (corresponding to an internal forcer temperature of 80°C) a 1 metre thrust rod will expand typically by 250 microns.

⁽³⁾ Maximum error over 1 metre under constant operating conditions.

FORCER OVER TEMPERATURE SENSOR



It is strongly recommended that the forcer over-temperature sensor is connected to the drive amplifier or servo controller **at all times** in order to reduce the risk of damage to the forcer due to excessive temperatures.

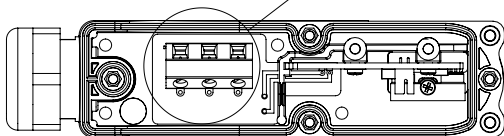
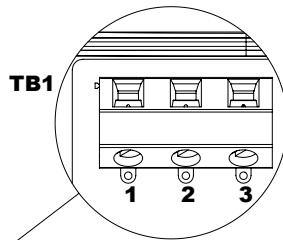
Protection is provided by three positive temperature coefficient (PTC) thermistors embedded in the forcer phases. As the forcer phase temperature approaches 100°C, the PTC thermistors exhibits a sharp increase in electrical resistance. This change in resistance can be detected by circuitry within the drive amplifier or servo controller and used to reduce or disable the output of the drive amplifier in order to protect the forcer.

SPECIFICATION	VALUE	units
Resistance in the temperature range -20°C to + 70°C	60 to 750	Ohms
Resistance at 85°C	≤1650	Ohms
Resistance at 95°C	≥3990	Ohms
Resistance at 105°C	≥12000	Ohms
Maximum continuous voltage	30	Vd.c.

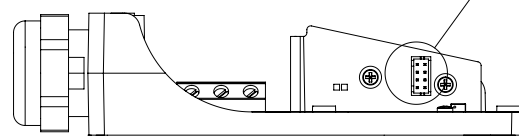
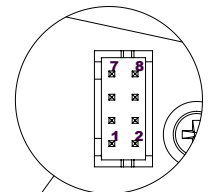
FORCER ELECTRICAL CONNECTIONS

Connections are made within the termination box.

PIN NUMBER	FUNCTION
1	Phase U
2	Phase V
3	Phase W
Chassis	Earth/Screen



PIN NUMBER	FUNCTION
1	+SIN
2	-SIN
3	+COS
4	-COS
5	+5Vd.c.
6	0V
7	+TH (Thermistor)
8	-TH (Thermistor)



CABLE TYPE

The STB has two separate cables providing connections for forcer power and position sensor. Cable types are available in 3 metre, 5 metre and 10 m lengths.

Cables are suitable for continuous flex or energy chain applications.

OPTION R SPECIFICATION	POWER	SENSOR
Overall diameter (nominal)	8.0mm	5.8mm
Outer jacket material	PUR	PUR
Number of conductors	4	4 x twisted pair
Size of conductors	1.5mm ² (16 AWG)	0.14mm ² (26AWG)
Screened / Unscreened	Screened	Screened
Minimum bending radius - flexible routing	42mm	42mm
Operating temperature - flexible routing	-15°C to +80°C	-15°C to +80°C
Operating temperature - fixed routing	-30°C to +80°C	-30°C to +80°C

CABLE TERMINATION

The STB cable is available with three termination options. **Option F** has the wire ends stripped and solder tinned ready for termination. All other options are terminated with connectors that plug directly into the desired amplifier. The connections for all options are shown below:

SENSOR FUNCTION	D - (XTL-S)	N - (ESR-Pollmeier)	F - (Flying leads)
+SIN	14	6	Blue
-SIN	13	7	Red
+COS	12	11	White
-COS	11	12	Brown
+5Vd.c.	4	10	Yellow
0V	5	15	Green
+TH (Thermistor)	10	5	Pink
-TH (Thermistor)	15	15	Grey
SCREEN	1+ shell	Shell	SCREEN
Connector type	15-way high density D	15-way high density D	-
Amplifier connection	J8	X6.2	-
POWER FUNCTION			
Forcer phase U	4	U	Black <u>1</u>
Forcer phase V	3	V	Black <u>2</u>
Forcer phase W	2	W	Black <u>3</u>
Earth (forcer body)	1	PE	Green/Yellow
SCREEN	1	Shell	SCREEN
Connector type	4-way 5mm pluggable terminal	4-way pluggable terminal	-
Amplifier connection	J2	X3	-

ENVIRONMENT

The STB is intended for use in an environment within the following conditions: -

SPECIFICATION	VALUE
Operating temperature	0°C to +40°C
Storage temperature	-25°C to +70°C
Ingress protection	IP67
Altitude (above mean sea level)	1000m
Overvoltage category	II
Pollution degree	2
EMC	light industrial

In addition, the STB is available with two environmental coating options. The forcer body is coated as standard with a 25 micron layer of black anodise that is suitable for general use. **Option H** has the forcer body coated with a 90 micron layer of hard natural anodise that is suitable for harsher environments. This option is available at a minimum quantity of 25 pieces per year.

ORDER CODES

Forcer

STB25 □ □ □ - □ - □ □ □ □

Forcer
04, 06, 08, 10

Winding
S - Series
P - Parallel

Environment
S - Standard
H - Harsh (on request)

Cable Termination
D - Xenus (XTL-S)
F - Flying leads
N - ESR Pollmeier

Cable Length
03 - 3 m
05 - 5 m
10 - 10 m

Cable Type
R - Robotic

Thrust Rod

TRB25 - □ □ □ □

Thrust rod length

0226	0354	0482	0611	0739	0918	1175	1431	1688
0252	0380	0508	0636	0765	0970	1226	1483	1739
0277	0405	0534	0662	0790	1021	1278	1534	
0303	0431	0559	0688	0816	1072	1329	1585	
0329	0457	0585	0713	0867	1124	1380	1637	

Length in mm