

- Microstepping
- Space Saving / Reduced Wiring by Compact Drive
- Software Damping
- Run/Stop Signal Output





CE







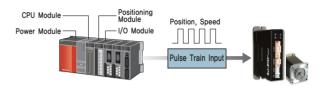






1) Standalone Motion Control

Ezi-STEP MINI is a standalone stepping motor control system that drives the motor by receiving pulse signals from the positioning module (pulse oscillator).



2) Microstep and Filtering

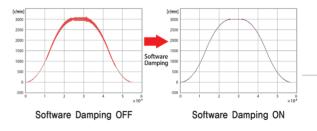
The high-performance MCU operates at step resolutions of 1.8° up to maximum 0.0072° (1/250 steps) and Ezi-STEP adjusts PWM control signal in every 25µsec, which makes it possible for more precise current control, resulting in high-precision Microstep operation. In addition, Ezi-STEP applies filtering control to enable smooth operation even at very low-speed.

3) Software Damping

Motor vibration is created by magnetic flux variations of the motor, lower current from the drive due to back-emf from the motor at high speeds and lowering of phase voltages from the drive,

Ezi-STEP drive detects these problems and the MCU adjusts the phase of the current according to the pole position of the motor, drastically suppressing vibration.

This allows the smooth operation of the motor at high speeds.

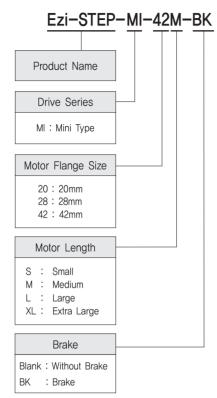


* This is real measured speed that using 100,000 P/R encoder.

4 Signal Output for Motion Monitoring

Ezi-STEP outputs the Run/Stop signal during operation, so you can check whether the motor is operating normally through the host controller.

• Ezi-STEP MINI Part Numbering



• Standard Combination

Unit Part Number	Motor Model Number	Drive Model Number				
Ezi-STEP-MI-20M	BM-20M	EzStep-MI-20M				
Ezi-STEP-MI-20L	BM-20L	EzStep-MI-20L				
Ezi-STEP-MI-28S	BM-28S	EzStep-MI-28S				
Ezi-STEP-MI-28M	BM-28M	EzStep-MI-28M				
Ezi-STEP-MI-28L	BM-28L	EzStep-MI-28L				
Ezi-STEP-MI-42S	BM-42S	EzStep-MI-42S				
Ezi-STEP-MI-42M	BM-42M	EzStep-MI-42M				
Ezi-STEP-MI-42L	BM-42L	EzStep-MI-42L				
Ezi-STEP-MI-42XL	BM-42XL	EzStep-MI-42XL				

• Combination with Brake

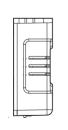
Unit Part Number	Motor Model Number	Drive Model Number
Ezi-STEP-MI-42S-BK	BM-42S-BK	EzStep-MI-42S
Ezi-STEP-MI-42M-BK	BM-42M-BK	EzStep-MI-42M
Ezi-STEP-MI-42L-BK	BM-42L-BK	EzStep-MI-42L
Ezi-STEP-MI-42XL-BK	BM-42XL-BK	EzStep-MI-42XL

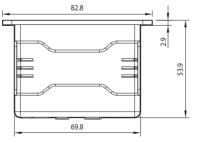
FASTECH Ezi-STEP MINI

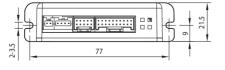
• Specifications of Drive

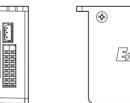
Motor	Model	BM-20 seriesBM-28 seriesBM-42 series									
Driver	Model	EzStep-MI-20 EzStep-MI-28 EzStep-MI-42 series									
Input	Voltage	DC24V±10%	DC24V±10%								
Contro	ol Method	Bipolar PWM drive with 32bit MCU									
Currer	nt Consumption	Max. 500mA (Except motor current)									
ng	Ambient Temperature	· In Use: 0~50℃ · In Storage: -20~70℃									
Operating Condition	Humidity	· In Use: 35~85% RH (Non-Condu · In Storage: 10~90% RH (Non-Co	0,								
	Vib. Resist.	0.5g	 1.5g								
	Rotation Speed	0~3,000r/min	0~3,000r/min								
Configurable Resolution [P/R] 500 1,000 1,600 2,000 3,200 3,600 4,000 5,000 6,400 8,000 10 20,000 25,000 36,000 40,000 50,000 6,400 8,000 10 (Set by DIP Switch) 500 <td< td=""></td<>											
	Max. Input Frequency	500kHz (Duty 50%)									
Function	Error Types	Over Current Error, Over Speed Error, Step Out Error, Over Temperature Error, Over Regenerated Volt- age Error, Motor Connect Error, Motor Voltage Error, System Error, ROM Error									
	LED Display	Power Status, Alarm Status, Motor	Rotation Direction								
	STOP Current Selection	10~100% (Set by DIP Switch)									
	Pulse Input Mode	1-Pulse / 2-Pulse (Set by DIP Swi	1-Pulse / 2-Pulse (Set by DIP Switch)								
	Rotation Direction	CW/CCW (Set by DIP Switch)									
	Speed/Position Control Command	Pulse Train Input (Photocoupler In	put)								
/0 gnal	Input Signals	Position Command Pulse, Alarm Re	eset/Motor Free (Photocoupler Input)							
I/O Signal	Output Signals	Alarm, Run/Stop (Photocoupler Out	tput)								

• Dimensions of Drive [mm]









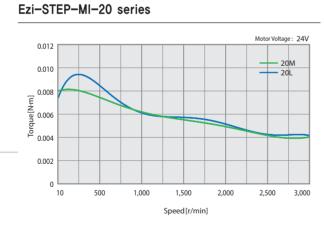
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FASTECH Ezi-STEP MINI

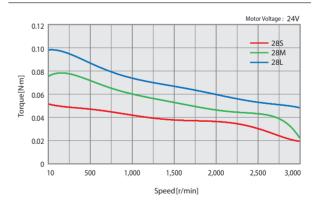
• Specifications of Motor

MODEL		BM-20 series		BM-28 series		BM-42 series						
UNIT			UNIT	20M	20L	28S	28M	28L	42S	42M	42L	42XL
DRIVE METHOD			-	Bipolar	Bipolar							
NUMBER OF PH	IASES		-	2 Phase								
CURRENT per F	PHASE		A/Phase	0.5	0.5	0.95	0.95	0.95	1.2	1.2	1.2	1.2
MAXIMUM HOLD TORQUE	MAXIMUM HOLDING TORQUE		N∙m	0.016	0.025	0.069	0.098	0.118	0.32	0.44	0.5	0.65
ROTOR INERTIA		g·cm ²	2.5	3.3	9.0	13	18	35	54	77	114	
WEIGHTS		kg	0.053	0.078	0.115	0.174	0.202	0.238	0.303	0.374	0.508	
LENGTH(L)	LENGTH(L)		mm	28	38	32	45	50	34	40	48	60
	DIS-	3mm		18	18	30	30	30	22	22	22	22
PERMISSIBLE	TANCE FROM	8mm	N	30	30	38	38	38	26	26	26	26
RADIAL LOAD	END OF	13mm	- IN	-	-	53	53	53	33	33	33	33
	SHAFT	18mm	-	-	-	-	-	-	46	46	46	46
PERMISSIBLE AXIAL LOAD N				Lower than Motor Unit's Weight								
INSULATION RESISTANCE MΩ			Min. 100(When measured with a DC500V insulation resistance meter)									
INSULATION CLASS -			CLASS E	CLASS B(130°C)								
OPERATING TEN	IPERA	TURE	C	$0 \sim 55$								

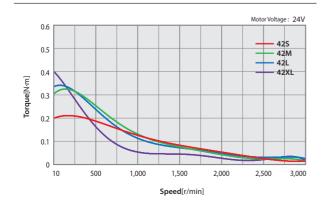
• Torque Characteristics of Motor



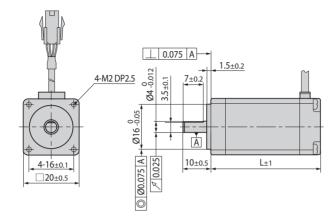
Ezi-STEP-MI-28 series



Ezi-STEP-MI-42 series

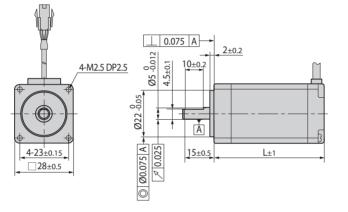


• Dimensions of Motor [mm]



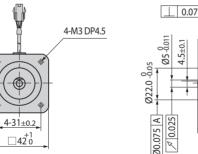


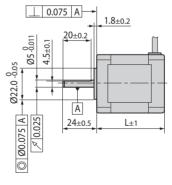
Model Name	Length(L)
BM-20M	28
BM-20L	38





Model Name	Length(L)
BM-28S	32
BM-28M	45
BM-28L	50





Model Name	Length(L)
BM-42S	34
BM-42M	40
BM-42L	48
BM-42XL	60

• Specifications of Motor with Brake

			Electromagnetic Brake					Permissible Radial Load [N]				Permissi-		
Unit Part Number	Motor Model Number	Туре		Rated Current	Power Con- sumption	Friction	woight		Distance from and of Shaft [mm]			Axial		
				[A]	[W]			3	8	13	18	[14]		
Ezi-STEP-MI-42S-BK	BM-42S-BK						0.500					Must be		
Ezi-STEP-MI-42M-BK	BM-42M-BK	-excitation		excitation	DC24V	0.0	F	0.0	0.560	00	20	22	40	Lower
Ezi-STEP-MI-42L-BK	BM-42L-BK						+10%	0.2	5	0.2	0.630	22	26	33
Ezi-STEP-MI-42XL-BK	BM-42XL-BK						0.770					Weight		

* Electronic Brake cannot be used for braking. Position hold purpose only when power OFF.

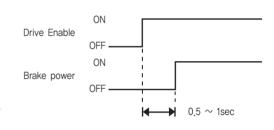
* The weight means Motor Unit Weight including Motor and Electronic Brake,

* Motor Model Number is combined model name of Motor and Brake.

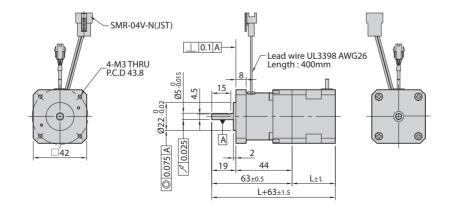
* Motor specification and torque characteristic are same as Standard Motor.

* Brake Operation Timing Chart

Ezi-STEP MINI controls Brake by Drive automatically. Please refer to below Timing Chart when Brake is controlled by the upper controller other than using Ezi-STEP MINI Brake control. Otherwise, Drive might malfunction and loads might fall down. Also, please do not operate Brake during motor operation to prevent damage.



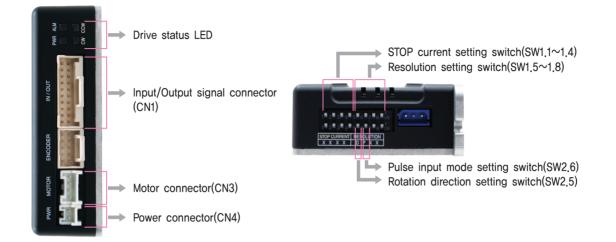
Dimensions of Motor with Brake [mm]





Model Name	Length(L)
BM-42S	34
BM-42M	40
BM-42L	48
BM-42XL	60

• Settings and Operation



1. Drive Status LED

Name	Color	Function	Description
PWR	Green	Power Input Indication	LED is turned ON when power is applied
ALM	Red	Alarm Indication	LED blinks when an error occurs.
CW	Yellow	Rotation Direction Indication	LED is turned on when the motor rotates CW.
CCW	Orange	Rotation Direction Indication	LED is turned on when the motor rotates CCW.

♦ List of error types by the number of LED blinking

No.	Error Type	Causes	
1	Over Current Error	The current through power devices in drive exceeds the limit.*1	-
2	Over Speed Error	The motor speed exceeds 3,000r/min.	_
3	Step Out Error	The motor does not follow the pulse input normally,	_
5	Over Temperature Error	Internal temperature of the drive exceeds 85°C.	
6	Over Regenerative Voltage Error	Back-EMF is higher than 50V.	0.5s 2s
7	Motor Power Error	There is a problem with the connection between the drive and the motor.	Alarm LED flash (e.g., Step Out Error)
9	Motor Voltage Error	The voltage supplied to the motor is lower than 20V.	*1: Limit value depends on motor model.
11	System Error	There is a problem in the drive system (Watchdog Timer Out).	(Refer to the Manual)
12	ROM Error	Error occurs in parameter storage device(ROM).	_

2. STOP Current Setting Switch(SW1.1~SW1.4)

Switch No.			STOP Current (%)	Switch	Switch No.			CTOD Current (%)	
4	3	2	1	STOP Current (%)	4	3	2	1	STOP Current (%)
ON	ON	ON	ON	10	OFF	ON	ON	ON	90
ON	ON	ON	OFF	20	OFF	ON	ON	OFF	100
ON	ON	OFF	ON	30	OFF	ON	OFF	ON	10
ON	ON	OFF	OFF	40	OFF	ON	OFF	OFF	10
ON	OFF	ON	ON	50	OFF	OFF	ON	ON	10
ON	OFF	ON	OFF	60	OFF	OFF	ON	OFF	10
ON	OFF	OFF	ON	70	OFF	OFF	OFF	ON	10
ON	OFF	OFF	OFF	80	OFF	OFF	OFF	OFF	10

Switch No.			D/D	Switch	Switch No.			D/D	
8	7	6	5	P/R	8	7	6	5	P/R
ON	ON	ON	ON	500	OFF	ON	ON	ON	6,400
ON	ON	ON	OFF	1,000	OFF	ON	ON	OFF	8,000
ON	ON	OFF	ON	1,600	OFF	ON	OFF	ON	10,000
ON	ON	OFF	OFF	2,000	OFF	ON	OFF	OFF	20,000
ON	OFF	ON	ON	3,200	OFF	OFF	ON	ON	25,000
ON	OFF	ON	OFF	3,600	OFF	OFF	ON	OFF	36,000
ON	OFF	OFF	ON	4,000	OFF	OFF	OFF	ON	40,000
ON	OFF	OFF	OFF	5,000	OFF	OFF	OFF	OFF	50,000

3. Resolution Setting Switch(SW1.5~1.8)

4. Rotation Direction Setting Switch(SW2.5)

Name	Function	Description			
D	Motor Rotation Direction Setting	It determines the rotation direction of the motor. The rotation direction indicated in the catalog is based on CW input. ON: CCW(-Direction) OFF: CW(+Direction)			

Rotation Direction Setting Switch: ON

CCW Direction

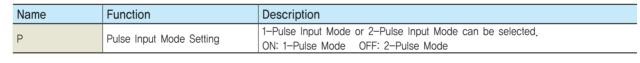


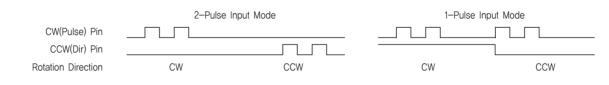


Rotation Direction Setting Switch: OFF

CW Direction

5. Pulse Input Mode Setting Switch(SW2.6)

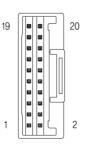




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No.	Function	I/O	
1	CW+(Pulse+)	Input	
2	CW-(Pulse-)	Input	
3	CCW+(Dir+)	Input	
4	CCW-(Dir-)	Input	
11	Alarm	Output	
12	Run/Stop	Output	
14	Alarm Reset /	Input	
14	Motor Free	Input	
19	EXT_GND	Input	
20	EXT_DC24V	Input	



7. Motor Connector(CN3)

No.	Function	I/O
1	B Phase	Output
2	B Phase	Output
3	A Phase	Output
4	A Phase	Output

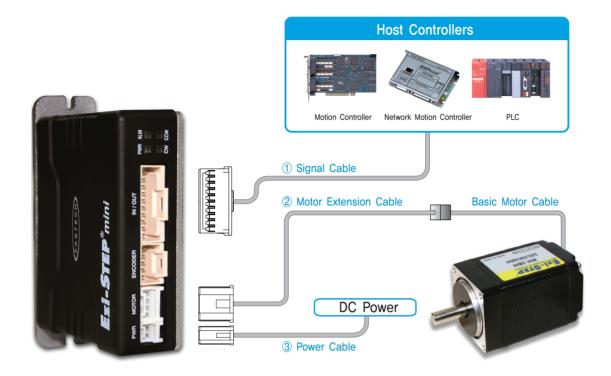


8. Power Connector(CN4)

No.	Function	I/O
1	DC24V	Input
2	GND	Input



• System Configuration



Cable Type	Max. Length	Remarks
① Signal Cable	20m	
② Motor Extension Cable	20m	Options (Sold separately)
③ Power Cable	2m	
Basic Motor Cable	0.3m (Basic length)	Basic cables are attached to motors.

1. Accessories

Connectors

These are connector specifications for drive cabling.

Purpose		Item	Part Number	Manufacturer
Power		Housing	PAP-02V-S	JST
(CN4)		Terminal	SPHD-001T-P0.5	121
	Drive Side (CN3) Motor Side	Housing	PAP-04V-S	JST
Matar		Terminal	SPHD-001T-P0.5	121
Motor		Housing	5557–04R	
		Terminal	5556T	MOLEX
Signal		Housing	501646-2000	
(CN1)		Terminal	501648-1000(AWG 26~28)	MOLEX

* The connectors above are supplied with the product. If you are using other parts, please make sure they meet the specifications,

2. Options

① Signal Cable

These are the cables to connect Ezi-STEP MINI drive and other input/output devices.

Purpose	Part Number	Length [m]	Cable Type	Remarks
	CSVI-S-001F	1		
	CSVI-S-002F	2	Normal Cable	
	CSVI-S-003F	3	Normal Cable	Maximum Length: 20m
Drive 1/0 Device Connection	CSVI-S-005F	5		
Drive – I/O Device Connection	CSVI-S-001M	1	Robot Cable	
	CSVI-S-002M	2		
	CSVI-S-003M	3		
	CSVI-S-005M	5		

* If you need cables with length(in units of 1m) not listed on the table, please contact FASTECH for more information.

2 Motor Extension Cable

These are the cables to connect Ezi-STEP MINI drive and the motor.

Purpose	Part Number	Length [m]	Cable Type	Remarks
	CMNB-M-001F	1		
	CMNB-M-002F	2	Normal Cabla	
	CMNB-M-003F	3	Normal Cable	Maximum Length: 20m
Drive – Basic Motor Cable	CMNB-M-005F	5		
Connection	CMNB-M-001M	1		
	CMNB-M-002M	2		
	CMNB-M-003M	3	Robot Cable	
	CMNB-M-005M	5		

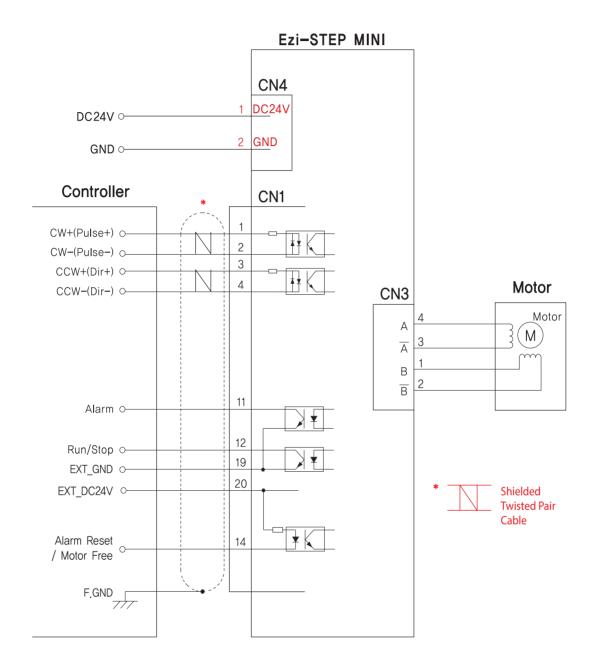
* If you need cables with length(in units of 1m) not listed on the table, please contact FASTECH for more information.

③ Drive Power Cable

These are the cables to connect Ezi-STEP MINI drive and the power.

	Purpose	Part Number	Length [m]	Cable Type	Remarks	
	Drive – Power Connection	CMNB-P-001F	1		Maximum Length: 2m	
		CMNB-P-002F	2	Normal Cable		
		CMNB-P-001M	1	Dahat Oakla		
		CMNB-P-002M	2	Robot Cable		

• External Wiring Diagram



FASTECH Ezi-STEP MINI

In order to use the products listed in this catalog safely and correctly, be sure to read the instruction manual before using the product,

% When connects I/O cable between controller and drive, please turn off the power of both controller and drive to prevent electric shock or to protect the drive from any damage.

MEMO



MEMO



Fast, Accurate, Smooth Motion

FASTECH Co., Ltd.

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