## TA26

## series



## Product Segments

## - Comfort Motion

TiMOTION's TA26 series electric linear actuator is designed for furniture applications such as recliners or lift chairs. This linear actuator is designed to function as a direct cut system, eliminating the need for a control box, offering a straightforward and cost effective alternative to complex electric actuation systems.

## General Features

Max. load
Max. speed at max. load
Max. speed at no load
Retracted length
Certificate
Output signals
Voltage
Color
Operational temperature range

4,000N (push); 2,000N (pull)
$6.1 \mathrm{~mm} / \mathrm{s}$
$24 \mathrm{~mm} / \mathrm{s}$
$\geq$ Stroke +120 mm
UL962
Hall sensor(s)
12/24V DC; 24V DC (PTC)
Black
$+5^{\circ} \mathrm{C} \sim+45^{\circ} \mathrm{C}$

Drawing

Standard Dimensions
(mm)


## Load and Speed

| CODE | Load (N) |  | Self Locking Force (N) |  | Typical Current (A) |  | Typical Speed (mm/s) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Push | Pull |  |  | No Load 32V DC | With Load 24V DC | No Load 32V DC | With Load 24V DC |
| Motor Speed (3800RPM, duty cycle 10\%) |  |  |  |  |  |  |  |  |
| A | 4000 | 2000 | 3000 | 4000 | 1.0 | 5.0 | 12.0 | 6.1 |
| B | 3000 | 2000 | 500 | 2500 | 1.0 | 4.5 | 18.0 | 7.5 |
| C | 2000 | 2000 | 350 | 1500 | 1.0 | 4.0 | 24.0 | 12.8 |

## Note

1 Please refer to the approved drawing for the final authentic value.
2 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in.

3 Operational temperature range: $-25^{\circ} \mathrm{C} \sim+65^{\circ} \mathrm{C}$
4 The current \& speed in table are tested with 24 V DC motor. With a 12 V DC motor, the current is approximately twice the current measured in 24 V DC; speed will be similar for both voltages.

5 The current \& speed in table are tested when the actuator is extending under push load.
6 The current \& speed in table and diagram are tested with TiMOTION control boxes, and there will be around $10 \%$ tolerance depending on different models of the control box. (Under no load condition, the voltage is around 32V DC. At rated load, the voltage output will be around 24 V DC)

7 The current \& speed in table and diagram are tested with a stable 24V DC power supply.

Motor Speed (3800RPM)

Speed vs. Load


Current vs. Load


TA26

| Voltage | $1=12 \mathrm{~V}$ | $2=24 \mathrm{~V}$ | $5=24 \mathrm{~V}, \mathrm{PTC}$ |
| :--- | :--- | :--- | :--- |
| Load and Speed | See page 2 |  |  |
|  |  |  |  |

## Stroke (mm) See page 5

## Retracted Length See page 5

(mm)
Rear Attachment $\quad 1=$ Plastic, clevis U, slot 6.2, depth 16.0, hole 10.2
$(\mathbf{m m})$

## See page 5

| Front Attachment | $1=$ Plastic, no slot, hole 8.2 | $4=$ Aluminum casting, clevis $U$, slot 6.2 , depth 17.0 , hole |
| :--- | :--- | :--- |
| $(\mathbf{m m})$ | $2=$ Plastic, no slot, hole 10.2 | 10.2 |
| See page 5 | $3=$ Aluminum casting, clevis $U$, slot 6.2 , depth 17.0, hole |  |
|  | 8.2 |  |

Special Functions $\quad 0=$ Without
for Spindle Sub-

Assembly

| Functions for | $1=$ Two switches at full retracted / extended positions to cut current |
| :--- | :--- |
| Limit Switches | $2=$ Two switches at full retracted / extended positions to cut current +3 rd LS to send signal |
| See page 6 | 3 = Two switches at full retracted / extended positions to send signal |
|  | $4=$ Two switches at full retracted / extended positions to send signal + 3rd LS to send signal |
| Output Signals | $0=$ Without |


| Connector | 1 = DIN 6P, $90^{\circ}$ plug |  | $\mathrm{K}=1$ motor direct cut system |  |
| :---: | :---: | :---: | :---: | :---: |
| See page 6 | 2 = Tinned leads |  | $J=1$ motor direct cut system, with anti-pull cover |  |
|  | $3=$ Small 01P, plug |  | L = 1+1, 2 motors direct cut system |  |
|  | $\mathrm{P}=$ Molex 8P, $90^{\circ}$ plug, without anti-clip |  | S = 1+1, 2 motors direct cut system, with anti-pull cover |  |
| Cable Length (mm) | $0=$ Straight, 100 | $4=$ Straight, 1250 | $\begin{aligned} 8 & =\text { Curly, } 400 \\ K & =\text { Direct cut operation } \\ & \text { with single actuator. } \\ & \text { See page } 6 \end{aligned}$ | L = Direct cut operation with two actuators. See page 6 |
|  | 1 = Straight, 500 | $5=$ Straight, 1500 |  |  |
|  | $2=$ Straight, 750 | 6 = Straight, 2000 |  |  |
|  | 3 = Straight, 1000 | 7 = Curly, 200 |  |  |

## TA26 Ordering Key Appendix

## Retracted Length (mm)

1. Calculate $A+B=Y$
2. Retracted length needs to $\geq$ Stroke $+Y$

## A. Front Attach.

| $\mathbf{1 , 2}$ | +120 |
| :--- | :--- |
| $\mathbf{3 , 4}$ | +150 |

## B. Stroke (mm)

0~150
151~200
201~250 +5
251~300 +10

301~350 +15
351~400 +20

## Note

1 For stroke over $200 \mathrm{~mm},+5 \mathrm{~mm}$ for each increment of 50 mm stroke

## Rear Attachment (mm)

1 = Plastic, clevis U, slot 6.2 , depth
16.0, hole 10.2


## Front Attachment (mm)

1 = Plastic, no slot, hole 8.2
2 = Plastic, no slot, hole 10.2
3 = Aluminum casting, clevis $U$, slot 6.2, depth 17.0, hole 8.2

4 = Aluminum casting, clevis $U$, slot 6.2 , depth 17.0, hole 10.2

$\varnothing 8.2$

ø10.2



กั



## TA26 Ordering Key Appendix

## Functions for Limit Switches

## Wire Definitions

| CODE | Pin |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 (Green) | 2 (Red) | $\bigcirc$ (White) | 4 (Black) | 5 (Yellow) | 6 (Blue) |
| 1 | extend (VDC+) | N/A | N/A | N/A | retract (VDC+) | N/A |
| 2 | extend (VDC+) | N/A | middle switch pin B | middle switch pin A | retract (VDC+) | N/A |
| 3 | extend (VDC+) | common | upper limit switch | N/A | retract (VDC+) | lower limit switch |
| 4 | extend (VDC+) | common | upper limit switch | medium limit switch | retract (VDC+) | lower limit switch |

## Connector

$1=$ DIN 6P, $90^{\circ}$ plug

$K=1$ motor direct cut system
$L=1+1,2$ motors direct cut system

$2=$ Tinned leads

$P=$ Molex $8 P, 90^{\circ}$ plug, without anti-clip

$J=1$ motor direct cut system, with anti-pull cover

$S=1+1,2$ motors direct cut system, with anti-pull cover


## Terms of Use

The user is responsible for determining the suitability of TiMOTION products for a specific application. TiMOTION products are subject to change without prior notice.

